Is My Code Good Enough? Improving software through code review.

Mike Jarvis February 5, 2018 LSST DESC DE School

How do you know if your code is good?

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- **1. Try it out**
 - Run it on different kinds of data.
 - Validate it on runs with simulated data.

2. Tests

- Integration tests to check that parts work together well.
- **3. Code Review**

Unit tests check each component for accuracy, reliability, etc.

What is a code review?

- A developer submits code changes for review.
- One or more reviewers read the code and comment, typically asking for modifications.
- The developer responds either by changing the code appropriately or replying why those suggestions are not appropriate.
- Once the reviewers are satisfied, the code is merged into the main line (e.g. master branch).
- GitHub makes all of these steps very easy.



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on with C++ layer code as an implementation	Γ 3	
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ProTip! Type g p on any issue or pull request to go back to the pull request listing page.

Mike

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Why do code reviews?

Why do code reviews?

- Helps find errors in the code.
- Encourages developers to be more thorough in the first place.
- Ensures that code base has a fairly consistent style.
- Helps developers learn coding techniques from others on the team.
- Spreads familiarity with the code base. At least 2 people have looked in detail at any given piece of the code.
- Saves time in the long run.

Discuss in groups...

Missing tests

- Unit tests of all the new parts of the code
- Tests of typical use case
- Tests of corner cases or unusual situations
- Tests of invalid user input
- Regression tests where appropriate
- Integration tests with other parts of the code
- Validation code to check accuracy of calculations



rmjarvis reviewed on Aug 23, 2016

tests/test_inclined_exponential.py

81 82	+ +	np.testin
83	+	
84	+	



rmjarvis on Aug 23, 2016

Need to add some more testing aside from just the regression tests though.

- do_pickle in other test files.
- 2. Some tests of edge-on inclination == Pi/2.
- you impose on i.
- for a few inclination angles.
- enough image == flux.

Hide outdated

```
g.assert_array_almost_equal(ratio_core, np.mean(ratio_cor
                           err_msg = "Error in compariso
                           verbose=True)
```

Owner

1. Need to check the accuracy of the repr, pickling etc. cf. uses of the function

3. Should test close, but not quite edge-on. Probably on both sides of the magic cut-off

4. Should test that i==0 is functionally equivalent to an Exponential.

5. Check some basic properties like that kValue at k=maxK() is below maxk_threshold and that less than folding_threshold fraction of the light falls outside of r=Pi/stepK()

6. Sanity checks like kValue(0,0) == flux, centroid() == (0,0), total flux draw with large

API redesign

- Feels clunky in some typical uses.
- Seems prone to user error from misuse.
- Doesn't match corresponding API of other parts of the code.
- Won't be extensible enough given future development plans.
- Doesn't have the appropriate options for some use cases.

galsim/base.py			
646	+	warnings	
647	+	else:	
648	+	jac = np.dia	
649	+	new_obj = galsim	



rmjarvis on Sep 30, 2016 Owner

And AFAICT the thing that it enables is for people to write

```
gal = gal.expand(lambda wave: wave**1.2)
```

rather than

gal = ChromaticObject(gal).expand(lambda wave: wave**1.2)

So I guess I have a few questions/comments about this.

- much just be applied to things that are already chromatic.



2. Is the first syntax any clearer than the second? The second one isn't much more typing, and it seems useful to me to be explicit that you want to treat the galaxy as having a uniform (unit, dimensionless) SED and then expand it as a function of wavelength. So the extra ChromaticObject bit seems useful to keep.

3. I'm a little concerned that the former would more often be a bug in the code rather

than what the user really wanted e.a. They might have some function

Failures of tests

- Sometimes errors are very system-specific.
- versions, numpy versions, etc.
- service to perform for the team.

• Travis should catch errors on one of several standard systems.

 Helpful for others on development team to try new code on their own machines to get a variety of OS's, Python versions, gcc

Even if you don't have time to review the code, this is a useful

Tests pass on my Mac. I'm getting some failures on my Linux cluster (and based on previous issues I went so far as to do a completely clean install of this branch starting from rm -rf .scon*, but they persisted).

```
FAIL: test_sensor.test_sensor_wavelengths_and_angles
```

```
Traceback (most recent call last):
  File "/opt/python27/lib/python2.7/site-packages/nose-1.3.0-py2.7.egg/nose/case.py", line
   self.test(*self.arg)
  File "/home/rmandelb/git/GalSim/tests/galsim_test_helpers.py", line 542, in f2
   result = f(*args, **kwargs)
  File "/home/rmandelb/git/GalSim/tests/test_sensor.py", line 395, in test_sensor_wavelengt
   assert r4 > r1
AssertionError:
----- >> begin captured stdout << ------
Starting test_wavelengths_and_angles
Testing Wavelength and Angle sampling - i band
Flux = 3539:
                                                  radius
                                     peak
                          sum
                                    435.00
No lamb, no angles:
                         3503.0
                                                 0.309004
W/ lamb, no angles:
                          3502.0
                                     435.00
                                                 0.308952
No lamb, w/ angles:
                          3503.0
                                     429.00
                                                 0.308881
W/ lamb, w/ angles:
                          3503.0
                                     408.00
                                                 0.320105
check r4 > r1 due to added wavelengths and angles
r1 = 0.309004. r4 = 0.320105. 2*sigma r = 0.010086
```

 $+(\cdots)$

....

Owner

Style

- Make sure code is clear. **Readability is paramount.**
- Make sure classes, function names indicate what they do.
- Make sure variable names match style elsewhere in code.
- If style if very bad throughout, suggest using a linter.
- If some section is very hard to read because of style, suggest specific changes.

galsim/compound.py				
920	+	Initial	ization	
921	+			
922	+	@param	npoints	Nur
923	+	@param	hlr	Hal

rmjarvis on Oct 26, 2016

Owner

convention here.

Documentation

- Improve (or add) user documentation of new features.
- Add new features list to the CHANGELOG.
- Give overview of algorithm in in-line comments.
- Reference relevant papers where formulae or algorithms come from.
- If using Sphinx or similar, make sure new docs process correctly.
- Include new features in demos if appropriate.

galsim/phase_psf.py			
@@ -23,6 +23,9 @@			
	23	23	
where x, y are focal plan	24	24	
	25	25	
+Alternatively, drawing us	26		
+Fourier optics.	27		

rmandelb on Dec 21, 2016 Owner

jmeyers314 on Dec 26, 2016 Owner I rewrote the beginning of this file docstring:

Utilities for creating PSFs from phase screens.

For PSFs drawn using real-space or Fourier methods, these utilities essentially optics diffraction equation:

where x, y are focal plane coordinates and u, v are pupil plane coordinates.

For PSFs drawn with method='phot', an often significantly faster geometric app instead. To use photon-shooting without this approximation, set `geometric_sho creating the PSF.

Hide outdated

ne coordinates and u, v are pupil plane coordinate

ing photon-shooting can use a fast geometric opti

Be more explicit: this is now the default when photon-shooting such objects.

```
PSF(x, y) = int(|FT(aperture(u, v) * exp(i * phase(u, v, x, y, t)))|^2, dt)
```

Inefficient code

- Avoid gratuitously inefficient code, such as loops in Python that are easy to convert to a list comprehension or calculations that can be pulled out of a loop.
- But don't prematurely optimize. If it's not in a "tall pole" section of the code, readability is more important than speed.
- Try to keep the inefficient algorithm in unit tests (since it might be "true by inspection") to compare against a faster algorithm.
- Consider pulling repeated code out into a helper function.

galsim/phase_screens.py			
477	+	<pre>coefs = np.array(coer</pre>	
478	+	coefs[1:] * = np.cump	
479	+	coefs[:-1] *= np.cump	
480	+	return coefs	

according to some timeit tests I ran) is

rmjarvis on Oct 21, 2016 Owner

```
def generate():
    c = a * * n
    yield c
    for i in range(n):
        c *= (n-i)/(i+1) * b / a
        yield c
return np.fromiter(generate(), float, n+1)
```


jmeyers314 on Oct 21, 2016 Owner

Always happy to see a clever improvement. Switched to your algorithm.

Who should do the review?

- Ideally at least two other developers on the same project.
- Anyone who already worked on portions of the code being changed.
- Encourage junior developers to participate as reviewers.
- Users of the code are excellent as reviewers of API design and docs.
- Occasionally bring in outside expertise to review portions of the code. (E.g. DESC architects)

Who should do the review?

How can you make your code easier to review?

Discuss in groups...

How can you make your code easier to review?

Keep it short.

- The PR should cover a single topic.
- changes in a few hours at most.
- one set of related changes at a time.
- files or whitespace edits.

Ideally, a reviewer should be able to fully understand the code

• For large refactorings, perhaps break up into a few PRs covering

 In some cases, trivial changes can be pushed directly to master before the PR. E.g. splitting up the contents of a file into multiple

#715 #817

‰ Merged rmjarvis merged 26 commits into master from #715 on Oct 31, 2016

-O- Commits **26**

+ Files changed **43**

zunyibrt commented on Oct 19, 2016

Add support for reading in of unsigned int Images

zunyibrt and others added some commits on Oct 5, 2016 Add uint16 and uint32 template instantiations to Add uint16 and uint32 support to pysrc/Image.cpp -0-Add uint16 and uint32 support to image.py -0-Add uint16 and uint32 special cases to ImageArith -0-Add uint16/32 template instantiations to Noise.cp -**O**-Add uint16/32 templates to SBShapelet.cpp -**O**-Add more uint32/64 template instantiations to SBS -0-Add uint16/32 suport to Noise.h -0-Add uint16/32 support to pysrc/NumpyHelper.h -0-Fix a mistake in template instantiation for uint -0-

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Mem	ber + 😧 🎤 👎	Reviewers
		Assignees No one—assign yourself
Image.cpp	3bba8fd 84aef37 162dcb2	Labels None yet
h.h pp	fd18349 62dde2a	Projects None yet
Shapelet.cpp	1ba4119 5aa93b8	Milestone No milestone
in pysrc/Noise.cpp	1abd069 e011b78	Notifications

How can you make your code easier to review?

Summarize your changes

- Give the reviewers sufficient context about your code changes.
- List the major changes your PR includes
- Point out tricky corner cases that you considered.
- Discuss any algorithmic or API decisions that you struggled with.
- Make sure to reference any open issues that the PR resolves or where design discussions have happened.
- Can write inline comments yourself before reviewers take a look.

#809e Switch from boost::shared_ptr to std::shared_ptr #911

‰ Merged

rmjarvis merged 66 commits into noboost from #809e on Nov 8, 2017

Conversation 17

-O- Commits 66

+ Files changed 176

rmjarvis commented on Sep 20, 2017 • edited -

Here is the next installment in the effort to rid GalSim of the boost dependency.

This PR nominally is about switching from boost::shared_ptr to either std::shared_ptr or std::tr1::shared_ptr depending on which is available. At least one of these is available back to GCC 4.1, so I don't think there is any worry about people not having this option.

The other big result from this effort is to get rid of the NumpyHelper.h file. This has a lot of complicated wrapping details, especially when we wanted to return a numpy array allocated in C++, that were hard to transfer over to pybind11 (never mind cffi or other wrapping modes). Now everything that used to return a numpy array instead has the numpy array allocated in python and then passed in to C++ to be filled in. This vastly simplifies the wrapping layer code with respect to numpy arrays.

Along the way, i made a few other changes, partly to make that switch easier (in the pysrc code) and partly just as general code cleanup. Some of these also ended up in PR #904 as deprecations.

- Switched from SBProfile to _sbp as the name of the SBProfile attribute. Mostly so the C++-layer SBProfile object is not part of the public API. This means we don't need to have the SBProfile classes be picklable, which simplifies a lot of the wrapping requirements. All the python-layer classes are still fully picklable, but their _sbp attributes are not necessarily so.
- Changed the Image class image attribute to _image to make it an implementation detail rather than something that users should ever use.
- Rewrote Bounds and Position in python with _b and _p properties to return the version that is needed for any calls to the C++ layer.
- Similarly, rewrote GSParams, ShapeParams, and HSMParams in python with attributes that are used for C++ calls. This means that the python layer is responsible for the memory handling, which means

Edit

+ 😐 Owner

+5,899 -5,230

Reviewers	÷
jmeyers314	~
Assignees	₽
No one-assign yourself	
Labels	₽
None yet	
Projects	₽
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Notifications	

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3 participants

How can you make your code easier to review?

Discuss work while developing

- Don't wait until code review to get feedback on design choices.
- Use the issue page to propose several possible API designs and ask about potential downsides of each.
- Advertise validation results in issue page before code is ready for review.
- Assign as code reviewers the people who participated in these discussions.

*

Conclusions

- Developing in a team needs a different workflow than when developing solo code.
- Code reviews save time in the long run and improve the quality of code.
- Both reviewing and being reviewed will improve your skillz.
- For further reading and recommendations from CI group, see the <u>LSST DESC Coding Guidelines</u>.